

ABSTRACT OF THE DISCLOSURE

A method and a system for controlling a force  
feedback member able to interact with another member,  
including a local model for calculating a set point  
5 addressed to the force feedback member from a plurality  
of variables, and a remote model for estimating  
interactions and variables of the other member, with  
updating on receiving data from another remote system,  
and resynchronizer means able to send a resynchronization  
10 message to the other system.

FOOTNOTES